Causal Inference with Spatio-temporal Data: Estimating the Effects of Airstrikes on Insurgent Violence in Iraq

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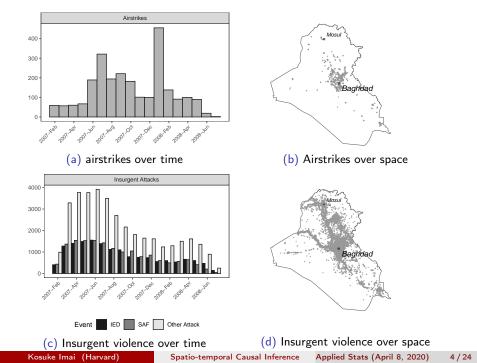
Joint work with Georgia Papadogeorgou (Duke), Jason Lyall (Dartmouth), and Fan Li (Duke)

Motivation

- Increasing availability of unstructured data in social sciences
 - $\bullet\,$ don't come in a nice matrix form \leadsto survey, official statistics
 - text, images, audio, video, etc.
- How should we draw causal inference from these new types of data?
- Causal inference with spatio-temporal data
 - a time series of maps as data
 - treatment and outcome event locations in a continuous space
 - applications: crime incidents, disease outbreaks, etc.
- Methodological challenges
 - spillover effects over space
 - 2 carryover effects over time
 - infinitely many possible treatment and outcome locations
- Current practice
 - arbitrary discretization of space
 - assumptions about spillover and carryover effects

Impacts of Airstrikes on Insurgent Violence in Iraq

- Airstrikes as a principal tool for combating insurgency in civil wars
- Debate: whether or not airstrikes reduce subsequent insurgent attacks (e.g., Kocher *et al.* 2011; Dell and Querubin 2018; Lyall 2019; Mir and Moore 2019)
- Methodological limitations:
 - discretize continuous space into aggregate geographical units
 - simplifying assumptions about spillover and carryover effects
- American air campaign in Iraq:
 - declassified USAF data from Jan. 2007 to July 2008 ("surge" period)
 - daily data with precise geolocation for airstrikes and insurgent attacks
- Drivers of airstrikes:
 - prior patterns of insurgent attacks and airstrikes
 - presence of American forces
 - settlement patterns and road networks
 - economic aid
 - intelligence about high-value targets (small fraction)



Contributions

- Causal inference with point process treatment and outcome
 - impossible to estimate causal effects of each treatment event
 - unrestricted spillover and carryover effects
 - $\bullet\,$ probability of each treatment realization is zero \rightsquigarrow lack of overlap
 - stochastic intervention based on the distribution of treatments
 - distribution of airstrikes as a military strategy
- Causal estimands under stochastic intervention
 - expected number of outcome events within a region of interest
 - various stochastic interventions

change the dosage while keeping the distribution identical
 change the distribution while keeping the overall dosage constant
 intervention over multiple time periods

- The proposed IPW (inverse probability of treatment) estimator
 - overlap and unconfoundedness assumptions
 - consistency and asymptotic normality
- Simulation studies and empirical application

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The Setup

- T time periods: $t = 1, 2, \ldots, T$
- Treatment variable
 - $\bullet~\Omega:$ set of all possibly infinite locations that can receive the treatment
 - $W_t(s) \in \{0,1\}$: binary treatment indicator for location s at time t
 - $W_t = \{W_t(s) : s \in \Omega\} \in \mathcal{W}$: treatment location map at time t
 - $S_{W_t} = \{s \in \Omega : W_t(s) = 1\}$: set of treatment-active locations at time t with $|S_{w_t}| < \infty$
 - $\overline{W}_t = (W_1, W_2, \dots, W_t)$: observed treatment history up to time t
- Outcome variable
 - $Y_t(s)$, Y_t , and \overline{Y}_t can be similarly defined
 - Potential outcome: $Y_t(\overline{w}_t)$ where $w_t \in \mathcal{W}$ is a realized treatment and $\overline{w}_t = (w_1, w_2, \dots, w_t) \in \mathcal{W}^t$ is a treatment history realization at time t.
 - Observed outcome: $Y_t = Y_t(\overline{W}_t)$
 - $S_{Y_t(\overline{w}_t)}$: set of outcome-active locations under treatment history \overline{w}_t
 - History of all potential outcomes up to time t: $\overline{\mathcal{Y}}_t = \{Y_{t'}(\overline{\boldsymbol{w}}_{t'}) : \overline{\boldsymbol{w}}_{t'} \in \mathcal{W}^{t'}, t' \leq t\}$
- Time-varying confounders: X_t , $\overline{\mathbf{X}}_t$, $X_t(\overline{\mathbf{w}}_{t-1})$, and $\overline{\mathcal{X}}_t$

Stochastic Intervention

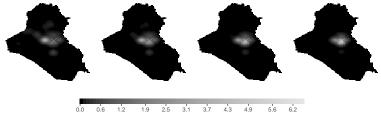
- Stochastic intervention: any distribution of treatment can be used
- We consider Poisson point process F_h
 - homogeneous Poisson point process with intensity h: For any disjoint region B₁, B₂,..., B_n ⊂ Ω, the number of events in each region B_i

$$N_{B_i}(W) \stackrel{\text{indep.}}{\sim} \operatorname{Poisson}(h|B_i|)$$

• non-homogeneous Poisson point process with intensity function $h(\omega)$:

$$N_{B_i}(W) \stackrel{\text{indep.}}{\sim} \operatorname{Poisson}\left(\int_{B_i} h(\omega) d\omega\right)$$

• Example:



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Causal Estimands

• Expected number of outcome-active locations in region *B* at time *t* under stochastic intervention *F_h* conducted at time *t*

$$\overline{N}_{Bt}(F_h) = \int_{\mathcal{W}} N_B(Y_t(\overline{\boldsymbol{W}}_{t-1}, w_t)) dF_h(w_t)$$

• Further average this quantity over time:

$$\overline{N}_B(F_h) = \frac{1}{T} \sum_{t=1}^T \overline{N}_{Bt}(F_h)$$

• We can compare the different interventions:

$$\tau_B(F_{h'},F_h) = \overline{N}_B(F_{h'}) - \overline{N}_B(F_h)$$

Stochastic Intervention over Multiple Time Periods

• Consider a non-dynamic stochastic intervention over *M* time periods

$$F_{\boldsymbol{h}} = F_{h_1} \times \cdots \times F_{h_M}$$
 where $\boldsymbol{h} = (h_1, h_2, \dots, h_M)$

• Expected number of outcome-active locations in region B at time t under stochastic intervention F_h conducted from time t - M + 1 to t

$$\overline{N}_{Bt}(F_{h}) = \int_{\mathcal{W}} \cdots \int_{\mathcal{W}} N_{B}(Y_{t}(\overline{W}_{t-M}, w_{t-M+1}, \dots, w_{t})) dF_{h_{M}}(w_{t-M+1}) \cdots dF_{h_{1}}(w_{t})$$

• Average this quantity over time:

$$\overline{N}_B(F_h) = \frac{1}{T-M+1} \sum_{t=M}^T \overline{N}_{Bt}(F_h)$$

• Comparison of different interventions:

$$\tau_B(F_{h'}, F_h) = \overline{N}_B(F_{h'}) - \overline{N}_B(F_h)$$

e.g., lagged effects with $h_M
eq h_M'$ and $\pmb{h}_{-M} = \pmb{h}_{-M}'$

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Assumptions

 Unconfoundedness: treatment is independent of all potential (past and future) paths for the outcome and time-varying confounders conditional on the observed history

$$f(W_t \mid \overline{\boldsymbol{W}}_{t-1}, \overline{\boldsymbol{Y}}_{t-1}, \overline{\boldsymbol{X}}_t, \{\overline{\mathcal{Y}}_T, \overline{\mathcal{X}}_T\}) = f(W_t \mid \overline{\boldsymbol{W}}_{t-1}, \overline{\boldsymbol{Y}}_{t-1}, \overline{\boldsymbol{X}}_t)$$

 \rightsquigarrow the generalization of the non-anticipating assumption for time-series experiments (Bojinov and Shephard, 2019)

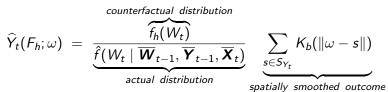
2 Overlap: there exists a constant $\delta_W > 0$ such that

$$\underbrace{f(W_t = w \mid \overline{W}_{t-1}, \overline{Y}_{t-1}, \overline{X}_t)}_{\text{propensity score}} > \delta_W \cdot \underbrace{f_h(w)}_{\text{density of } F_h} \quad \text{for all } w \in \mathcal{W}$$

 \rightsquigarrow the ratio $f_h(w)/f(W_t = w \mid \overline{W}_{t-1}, \overline{Y}_{t-1}, \overline{X}_t)$ is bounded

The Proposed Estimator

- Inverse probability of treatment weighting (IPW)
- Kernel smoothing of spatial point patterns
- Estimated outcome surface at $\omega \in \Omega$



where K_b is the scaled Kernel function with bandwidth parameter b

• Estimated number of outcome-active locations in region B

$$\widehat{\overline{N}}_{Bt}(F_h) = \int_B \widehat{Y}_t(F_h;\omega) d\omega$$

Averaging over time

$$\widehat{\overline{N}}_B(F_h) = \frac{1}{T} \sum_{t=1}^T \widehat{\overline{N}}_{Bt}(F_h)$$

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Estimation for Intervention over Multiple Time Periods M

• Estimated outcome surface at $\omega \in \Omega$

$$\widehat{Y}_{t}(F_{\boldsymbol{h}};\omega) = \prod_{j=t-M+1}^{t} \frac{f_{h_{t-j+1}}(W_{j})}{\widehat{f}(W_{j} \mid \overline{\boldsymbol{W}}_{j-1}, \overline{\boldsymbol{Y}}_{j-1}, \overline{\boldsymbol{X}}_{j})} \sum_{s \in S_{Y_{t}}} K_{b}(\|\omega - s\|)$$

where K_b is the scaled Kernel function with bandwidth parameter b
Estimated number of outcome-active locations in region B

$$\widehat{\overline{N}}_{Bt}(F_{h}) = \int_{B} \widehat{Y}_{t}(F_{h};\omega) d\omega$$

Averaging over time

$$\widehat{\overline{N}}_B(F_h) = \frac{1}{T-M+1} \sum_{t=M}^T \widehat{\overline{N}}_{Bt}(F_h)$$

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Asymptotic Normality and Variance Estimation

• Suppose that there exists v such that

$$\frac{1}{T-M+1}\sum_{t=M}^{T} v_t \stackrel{p}{\longrightarrow} v \quad \text{as } T \longrightarrow \infty$$

where
$$v_t = \mathbb{V}\left(\widehat{\overline{N}}_{Bt}(F_h) \mid \overline{W}_{t-M}, \overline{\mathcal{Y}}_T, \overline{\mathcal{X}}_T\right).$$

• Then, under some regularity conditions, we have,

$$\sqrt{T}\left(\widehat{\overline{N}}_{B}(F_{\boldsymbol{h}})-\overline{N}_{B}(F_{\boldsymbol{h}})\right)\overset{d}{\longrightarrow}\mathcal{N}(0,v)$$

where the proof is based on the martingale theory

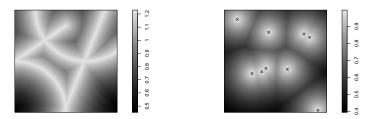
- Time-specific variance v_t cannot be estimated
- We use the upper bound $v_t \leq \mathbb{E}\left(\widehat{\overline{N}}_{Bt}(F_{\boldsymbol{h}})^2 \mid \overline{\boldsymbol{W}}_{t-M}, \overline{\mathcal{Y}}_{\mathcal{T}}, \overline{\mathcal{X}}_{\mathcal{T}}\right)$
- Estimated propensity score ~→ smaller variance

Simulation Studies: Setup

- Times series of length T = 200, 400, 500 on unit square $\Omega = [0, 1]^2$
- Two time-invariant confounders $X^1(\omega), X^2(\omega)$:

draw hypothetical road networks using lines and arcs
 confounder as exponential decay of distance to the closest line (arc)

- Two time-varying confounders $X^3(\omega), X^4(\omega)$:
 - draw points from non-homogeneous Poisson process based on X¹(ω)
 confounder as exponential decay of distance to the closest point



(a) Time-invariant confounder $X^{1}(\omega)$ (b) Time-varying confounder $X^{3}(\omega)$

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• Treatment assignment: non-homogeneous Poisson point process

$$\lambda_t^{W}(\omega) = \exp\{\alpha_0 + \alpha_{\mathbf{X}}^{\top} \mathbf{X}_t(\omega) + \alpha_{W} W_{t-1}^*(\omega) + \alpha_{Y} Y_{t-1}^*(\omega)\}$$

where $W_{t-1}^*(\omega) = \exp\{-2D_W(\omega)\}$ and $Y_{t-1}^*(\omega) = \exp\{-2D_Y(\omega)\}$ with D_W and D_Y being the distance from ω to the closest treatment and outcome active locations at t-1

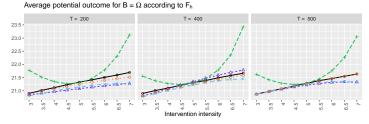
• Outcome: non-homogeneous Poisson point process

$$\lambda_t^{Y}(\omega) = \exp\{\gamma_0 + \gamma_{\mathbf{X}}^{\top} \mathbf{X}_t(\omega) + \gamma_W W^*_{(t-3):t}(\omega) + \gamma_Y Y^*_{t-1}(\omega)\}$$

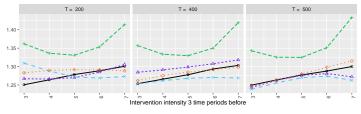
where $W^*_{(t-3):t}(\omega) = \exp\{-2D^*_W(\omega)\}$ with D^*_w being the distance from ω to the closest treatment active locations from time t-3 to t

Stochastic interventions: homogeneous Poisson point process
F_h = F^M_h with intensity h = 3,...,7 with M = 1,3,7,30
F_h = F_{h₁} × F_{h₂} × F_{h₃} where h₃ = 3,...,7 and h₁ = h₂ = 5

Simulation Results



Average potential outcome for B = [0.75, 1]², lagged intervention with M = 3



-- Truth ---- Estimate-True PS -+- Unadjusted ---- Estimate-Est PS ---- Estimate-Est PS-Hajek

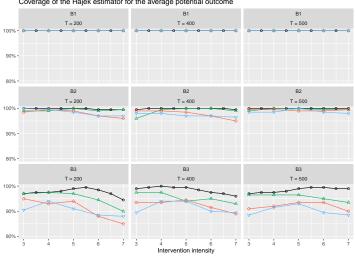
• Estimation improves as T increases and worsens as h increases • Hájek adjustment substantially improves the performance

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Coverage of Hájek Estimator's 95% Confidence Intervals



Coverage of the Hajek estimator for the average potential outcome

M → 1 → 3 → 7 → 30

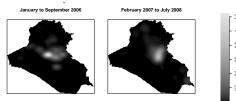
• Performance improves as T increases and worsens as M increases

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Empirical Analysis: Setup

• Estimate the baseline treatment distribution $\phi_0(\omega)$ based on the airstrikes data from January to September, 2006



- How does increasing airstrikes affect insurgent violence?
 → vary c > 0 for h(ω) = c ⋅ φ₀(ω)
- When the set of the
- How does the shift in the prioritization of certain locations for airstrikes change the spatial pattern of insurgent attacks?
 → vary α > 0 for h_α(ω) = c_α · φ₀(ω)d_α(ω) with ∫_Ω h_α(ω)dω = c
 - power density ${\it d}_{lpha}(\omega) \propto {\it d}(\omega)^{lpha}$
 - $d(\omega) =$ the normal density centered at s_f with precision α

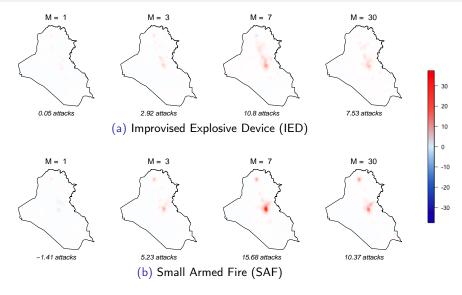
Propensity Score Model Specification

- Non-homogeneous Poisson point process
 - prior airstrikes over the last day, week, and month

$$\overline{W}_{t-1}^{*}(\omega) = \sum_{j=1}^{7} \sum_{s \in S_{W_{t-j}}} \exp\{-\|s - \omega\|\}$$

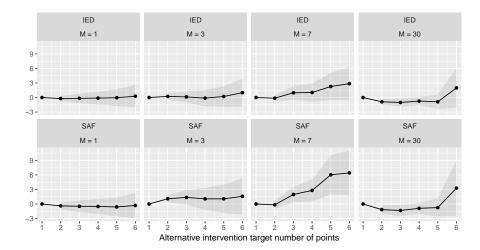
- prior insurgent attacks over the last day, week, and month
- prior show-of-force over the last day, week, and month
- amount of US aid in each district over the past month
- distances from major cities, road networks, rivers, and settlements
- log population of governorate (measured in 2003), temporal splines

Increasing the Expected Number of Airstrikes from 1 to 6 per Day Leads to More Insurgent Attacks

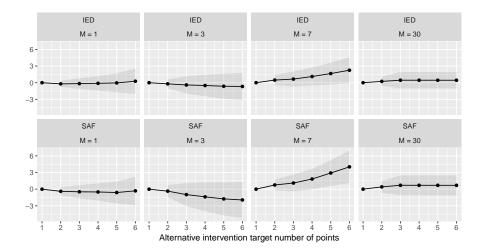


Spatio-temporal Causal Inference Appli

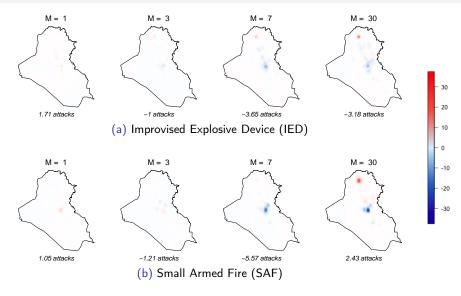
Effect of Increasing the Airstrikes for M Days on the Number of Insurgent Attacks within Baghdad



Effect of Increasing the Airstrikes *M* **Days Ago** on the Number of Insurgent Attacks within Baghdad



Increasing the Priority of Baghdad as a Focal Point of Airstrikes Shifts Attacks to Mosul when M is Large



Spatio-temporal Causal Inference Applied

Concluding Remarks

- A new approach to causal inference with spatio-temporal data
 - directly model point patterns without arbitrary aggregation
 - allow for unstructured spillover and carryover effects
- Key idea: stochastic intervention
 - consider treatment distributions rather than fixed treatment values
 - can handle infinitely many possible treatment locations
 - combine this with spatial smoothing for outcome point process
- Effects of airstrikes on insurgent attacks in Iraq
 - airstrike strategies as stochastic interventions
 - flexible estimation of spillover and carryover effects
- Future research:
 - causal inference with unstructured data such as texts
 - civilian casualty as mediator; comparison with hearts and minds

• Paper at https://imai.fas.harvard.edu/research/spatiotempo.html

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